Recommended Readings in Math and Programming before Pursuing the MQF Program

Rutgers Business School Master of Quantitative Finance Program

Section I Basic Knowledge of Mathematics

1. Calculus

Reference Book: Calculus, Gilbert Strang, Wellesley-Cambridge Press

- 1.1. Derivatives (Chapter 2) Derivative of a function; linear approximation; product, quotient and power rules.
- 1.2. Applications of the Derivative (Chapter 3)

Linear approximation; maximum and minimum problems; second derivatives; the mean value theorem and L'hopital's rule.

- 1.3. The Chain Rule (Chapter 4) The chain rule; implicit differentiation and related rates; inverse functions and their derivatives.
- 1.4. Integrals (Chapter 5)

Indefinite integrals and substitutions; the definite integral; the fundamental theorem and its applications; numerical integration.

- 1.5 Exponentials and Logarithms (Chapter 6) The exponential e^x; logarithms; powers instead of exponentials; Euler's method.
- 1.6 Techniques of Integration (Chapter 7) Integration by parts.
- 1.7 Applications of the Integral (Chapter 8) Probability and calculus; masses and moments.
- 1.8 Polar Coordinates and Complex Numbers (Chapter 9) Polar coordinates; complex numbers.
- 1.9 Infinite Series (Chapter 10) The geometric series; the Taylor series; power series.

1.10 Vectors and Matrices (Chapter 11)

Vectors and dot products; planes and projections; cross products and determinants; matrices and linear equations.

1.11 Partial Derivatives (Chapter 13)

Partial derivatives; tangent planes and linear approximations; gradients; the chain rule; maximum, minimum and saddle points; constraints and Lagrange multipliers.

1.12 Multiple Integrals (Chapter 14)

Double integrals; changing to better Coordinates; triple Integrals; cylindrical and spherical coordinates.

1.13 Vector Calculus (Chapter 15)

Green's theorem; surface integrals; the divergence theorem; Stokes' theorem

2. Linear Algebra

<u>Reference Book:</u> *Linear Algebra*, David Cherney, Tom Denton and Andrew Waldron Davis California, 2013. First Edition

2.1 Systems of Linear Equations (Chapter 2)

Gaussian elimination; elementary row operations; solutions sets for systems of linear equations.

2.2 Vectors in Space, n-Vectors (Chapter 4)

Addition and scalar multiplication in Rⁿ; hyperplanes; directions and magnitudes; vectors, lists and functions

2.3 Linear Transformations (Chapter 6)

The consequence of linearity; linear functions on hyperplanes; linear differential operators; bases.

2.4 Matrices (Chapter 7)

Linear transformations and matrices; properties of matrices; inverse matrix; LU decomposition.

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2.5 Determinants (Chapter 8)
The determinant formula; elementary matrices and determinants; properties of the determinant.
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- 2.6 Subspaces and Spanning Sets (Chapter 9) Subspaces; building subspaces.
- 2.7 Linear Independence (Chapter 10) Showing linear dependence; showing linear independence
- 2.8 Basis and Dimension (Chapter 11) Bases in Rⁿ; matrix of a linear transformation.
- 2.9 Eigenvalues and Eigenvectors (Chapter 12) Invariant directions; the eigenvalue-eigenvector equation; eigenspaces.
- 2.10 Diagonalization (Chapter 13) Change of basis; changing to a basis of eigenvectors.
- 2.11 Orthonormal Bases and Complements (Chapter 14) QR Decomposition; orthogonal complements.

3. Probability and Statistics

<u>Reference Book:</u> *Probability and Statistics with R*, Chapman and Hall, CRC Press 2008. Note: Students are recommended to study probability and statistics by using R.

3.1 A Brief Introduction to S(R). (Chapter 1).

R structures; data types in R; reading and outputting data; all data structures in R; how to write your own functions in R.

3.2 Exploring Data. (Chapter 2).

Displaying qualitative and quantitative data; summary measures of location and spread; bivariate and multivariate data.

3.3 General Probability and Random Variables (Chapter 3).

Sample space; set theory; conditional probability; the law of total probability and Bayes' rule; independent events; discrete random variables; mode, median and percentiles; expected values of discrete random variables; moments; continuous random variables; Markov's theorem and Chebyshev's inequality; weak law of large numbers; skewness; moment generating functions.

3.4 Univariate Probability Distributions (Chapter 4).

Discrete univariate distributions; continuous univariate distributions.

3.5 Multivariate Probability Distributions (Chapter 5).

Joint distribution of two random variables; independent random variables; conditional distributions; expected values, covariance and correlation; multinomial distribution; bivariate normal distribution.

3.6 Sampling and Sampling Distributions (Chapter 6). Sampling; Chi-square distribution; t-distribution; F-distribution.

3.7 Point Estimation (Chapter 7)

Mean square error; unbiased estimators; efficiency; consistent estimators; method of moments estimators; maximum likelihood estimators.

3.8 Confidence Intervals (Chapter 8)

Confidence intervals for population means and variances; confidence intervals based on large samples.

3.9 Hypothesis Testing (Chapter 9)

Type I and Type II errors; power function; UMP test; P-value; tests of significance; hypothesis tests for population means/variances/proportions.

- 3.10 Nonparametric Methods (Chapter 10) Goodness-of-fit tests (Chi-square/KS tests); bootstrapping.
- 3.11 Regression (Chapter 12)

Simple linear regression; multiple linear regression; OLS; properties of the fitted regression line; ANOVA approach to regression (SSR, SSE, SST and degrees of freedom); R square; T test; F test.

4. Differential Equations

<u>Reference book:</u> *Introduction to Differential Equations*, Jeffrey R. Chasnov, The Hong Kong University of Science and Technology.

- 4.1 Introduction to ODEs (Chapter 1).
- 4.2 First-order ODEs (Chapter 2).
- 4.3 Second-order ODEs (Chapter 3).
- 4.4 The Laplace Transform (Chapter 4).
- 4.5 Series Solutions (Chapter 5).
- 4.6 Systems of Equations (Chapter 6).
- 4.7 Nonlinear Differential Equations (Chapter 7).
- 4.8 Partial Differential Equations (Chapter 8).

Section II Coding Skills

5. C++

<u>Reference book</u>: C++ for Programmers, Paul J. Deitel and Harvey M. Deitel.

- 5.1 Introduction to C++ Programming (Chapter 2)
- 5.2 Introduction to Classes and Objects (Chapter 3)
- Classes; Objects; Member functions; Data members
- 5.3 Control Statements (Chapters 4&5)
- 5.4 Functions and an Introduction to Recursion (Chapter 6)
- 5.5 Arrays and Vectors (Chapter 7)
- 5.6 Pointers and Pointer-based Strings (Chapter 8)
- 5.7 Classes: A Deeper look (Chapters 9&10)
- 5.8 Operator Overloading: String and Array Objects (Chapter 11)
- 5.9 Inheritance (Chapter 12)
- 5.10 Polymorphism (Chapter 13)
- 5.11 Templates (Chapter 14)
- 5.12 Standard Template Library (Chapter 20)

6. Matlab

<u>Reference book:</u> Numerical Methods in Finance and Economics – A MATLAB-Based Introduction (Second Edition), Paolo Brandimarte, WILEY.

7. SAS

Reference book: The Little SAS Book, Lora D. Delwiche and Susan J. Slanghter, SAS Publishing.

8. R

Reference books:

An Introduction to R, W. N. Venables, D. M. Smith and the R Development Core Team. Probability and Statistics with R, Chapman and Hall, CRC Press 2008. Time Series Analysis and Its Applications with R Examples, Robert H. Shumway and David S. Stoffer, Springer.

9. VBA

<u>Reference books</u>: *Financial Modeling Using Excel and VBA*, Chandan Sengupta, WILEY. *Advanced Modeling in Finance Using Excel and VBA*, Mary Jackson and Mike Staunton, John Wiley & Sons, Ltd.